

CHRYSLER ECOVOYAGER SIMULATION

[http://www.leapcad.com/Transportation/Chrysler EcoVoyager Simulation.mcd](http://www.leapcad.com/Transportation/Chrysler_EcoVoyager_Simulation.mcd)

Ecovoyager - Vehicle, Motor, Road, and Enviro Params: Fixed Gears: 6,000,8000 RPM Pk Power

Max Motor Power:	Power _{max} := 268·hp	Fixed Two Gear Ratios:	GR ₁ := 14.3 GR ₂ := 7.4
Max Motor Torque:	T _{max} := 250·ft·lbf	Battery Energy:	Energy _{bat} := 16·kW·hr
GR _{1.5} := 8.2752·1.124		Tire Radius*:	r _{tire} := $\frac{30.3}{2}$ ·in
Max Force, F _{MaxTire}	F _{mtire1} := GR ₁ · $\frac{T_{max}}{r_{tire}}$	F _{mtire2} := GR ₂ · $\frac{T_{max}}{r_{tire}}$	F _{mtire1.5} := GR _{1.5} · $\frac{T_{max}}{r_{tire}}$
RPM := min ⁻¹			
Max Power, ω:	ω _{Pmax} := $\frac{Power_{max}}{T_{max}}$	RPM _{Pmax} := $\frac{\omega_{Pmax}}{2 \cdot \pi}$	RPM _{Pmax} = 5.63 × 10 ³ RPM
Constant Power vehicle velocity, v _{CP} :	v _{CP} := $\frac{Power_{max}}{F_{mtire1.5}}$	v _{CP} = 54.565 mph	Power _{max} = 268 hp
Time, in seconds:	t := 0, 0.5.. 30	Lotus Elsie Chassis	k := 10 ³
Time unit:	τ := 1·sec	Curb Weight:	M _{curb} := 2750·lb
Drag Coeff:	Cd := 0.35	Average Wind Velocity:	V _w := 0·mph
Cross Wind Drag Coff:	Cd _{cw} := 0.000014	Effective Cross Wind V:	V _{cw} := 0·mph
Shape Correction Factor:	SCF := 1	Frontal Area*:	A _{fg} := 59·in·70·in
Air Density:	ρ := 1.293· $\frac{gm}{liter}$	Frontal Area	A _f := A _{fg} ·SCF Af = 2.665 m ²
Road Rolling Resist:	RR _{road} := 0.002	Tire Rolling Resist, Hys:	RR _{tire} := 0.009 T _{hys} := 0· $\frac{sec}{m}$
Passengers2 := 170·lb	M _{batt} := ■ lb	θ (radians):	θ := atan(0.0)
Rotational Inertia Coeff:	k _m := 1.12	M _{gross} := M _{curb} + Passengers2	M _{gross} = 2.92 × 10 ³ lb

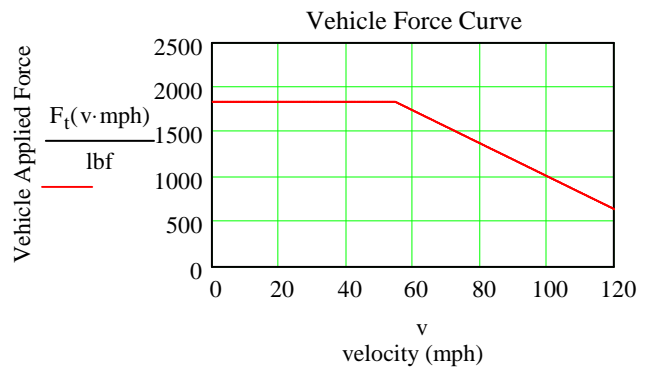
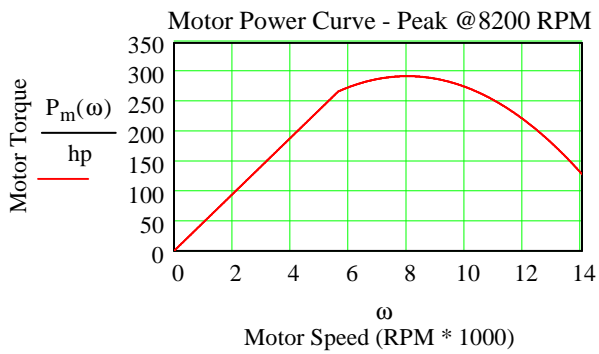
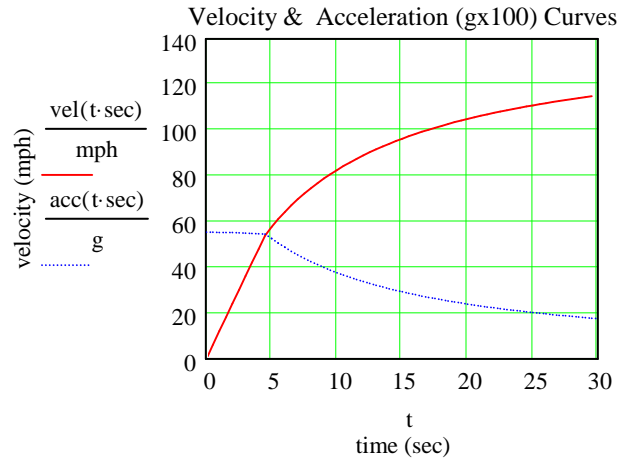
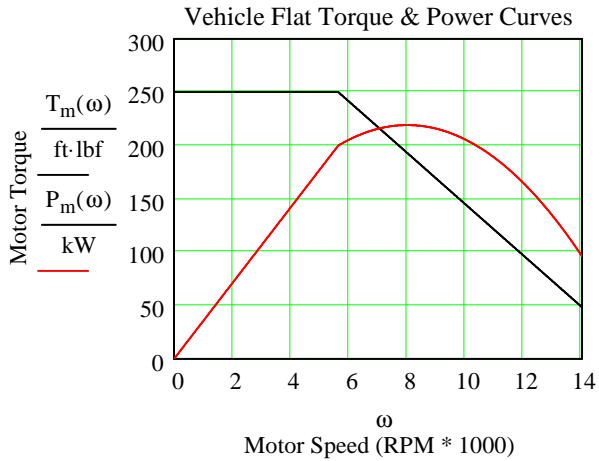
Vehicle Dynamics Equations:

Velocity at Torque Fall:	v _{T1} := 6100·RPM·2·π·r _{tire} ·GR ₁ ⁻¹	v _{T1} = 38.452 mph	
Velocity to RPM:	VtoR(v) := v·(k·2·π·r _{tire} ·RPM) ⁻¹	VtoR(61·mph)·GR ₂ = 5.008	
Road Resistance, Ft:	F _t (v) := M _{gross} ·g·[T _{hys} ·v·sin(θ) + (RR _{tire} + RR _{road})·cos(θ) + sin(θ)]		
Air Drag Force, Fa:	F _a (v) := 0.5·ρ·Cd·A _f ·[(v + V _w) ² ·Cd + Cd _{cw} ·(V _{cw}) ²]	ω _{fall} := 6·RPM	
Opposing Force, Fo:	F _o (v) := F _a (v) + F _t (v)	F _o (60·mph) = 66.25 lbf	ω _{fall} := RPM _{Pmax} ·k ⁻¹
Torque/Force Drop Curve:	T _{fall} (ω) := T _{max} ·[1 - (ω·RPM - ω _{fall})·((ω _{max} - ω _{fall})) ⁻¹]	ω _{max} := 16·RPM	
Torque Speed Relation:	T _m (ω) := if(ω·RPM ≥ ω _{fall} , T _{fall} (ω), T _{max})		
Net Tractive Force:	F _t (v) := if(v > 1000·mph, GR ₂ · $\frac{T_m(VtoR(v) \cdot GR_2)}{r_{tire}}$, GR _{1.5} · $\frac{T_m(VtoR(v) \cdot GR_{1.5})}{r_{tire}}$)		
Third Law of Motion: (a is acceleration)	a(v) := $\frac{F_t(v) - F_o(v)}{k_m \cdot M_{gross}}$	Power _{max} := P _m (8)	P _m (ω) := T _m (ω)·k·2·π·ω·RPM Power _{max} = 293.777 hp

Applying maximum motor torque, find the velocity starting from initial velocity = 0 mph.

V := 0·mph	vel(t) := root(V - ∫ ₀ ^t a(V)·τ dt, V)	vel(60·sec) = 127.59 mph	
Acceleration in g		acc(t) := a(vel(t·sec))·100	
Time := 0·sec	time(v) := root(v - vel(Time), Time)	time(60·mph) = 5.337 s	

ESTIMATED PERFORMANCE CURVES



Find the Single Charge (@SOC = 50%) Cruise Range for a given Velocity

Driving Pattern/Profile:

Assume we cruise at constant speed and start, stop, and regen braking every 15 minutes.

Drive Train Power Efficiency - Battery Loss to Force Commanded Vehicle Velocity:

State of Charge for generator is SOC_{gen} . **SOC_{gen} is 50% for recharge.** 320V HV battery idle power is P_o . 12V battery gives Accessory Power. The Traction Inverter Efficiency - $TInvE$, HV Power Electronics at Idle Efficiency - $IPEE$, and Gear Power Efficiency - GPE are 92.5%, 95%, and 90%, respectively. Brake Regen efficiency of kinetic energy is 70%. Then the number of starts per hour as a function of velocity, NS , $NumStarts(v, P_o)$, is

$$W4DE := 0.94 \quad TInvE := 0.925 \quad IPEE := 0.95 \quad GPE := 0.9 \quad \text{Regen} := 0.7 \quad v := 0, 2..80 \quad SOC_{gen} := 0.5$$

$$Power_{dissLoss}(v, P_o) := \frac{F_o(v) \cdot v}{TInvE \cdot GPE \cdot W4DE} + \frac{P_o \cdot watt}{IPEE} \quad RTEff := 0.92$$

$$Energy_{accel}(v) := Power_{max} \cdot time(v)$$

NS_o and NS are iterative converging estimates of $NumStarts$

$$NS_o(v) := 2 \cdot \left(\frac{50 \cdot \text{mph}}{v} \right)^2 \quad NS(v, P_o, S) := \frac{Energy_{bat} \cdot (1 - S) - NS_o(v) \cdot \left(\frac{Energy_{accel}(v)}{TInvE \cdot GPE \cdot W4DE} - \frac{Regen \cdot M_{gross} \cdot v^2}{2} \right)}{Power_{dissLoss}(v, P_o) \cdot 15 \cdot \text{min}}$$

$$NumStarts(v, P_o, S) := \text{floor} \left[\frac{Energy_{bat} \cdot (1 - S) - NS(v, P_o, S) \cdot \left(\frac{Energy_{accel}(v)}{TInvE \cdot GPE \cdot W4DE} - \frac{Regen \cdot M_{gross} \cdot v^2}{2} \right)}{Power_{dissLoss}(v, P_o) \cdot 15 \cdot \text{min}} \right]$$

$$Cruise_Range(v, P_o, S) := \frac{Energy_{bat} \cdot (1 - S) - NumStarts(v, P_o, S) \cdot \left(\frac{Energy_{accel}(v)}{TInvE \cdot GPE \cdot W4DE} - \frac{Regen \cdot M_{gross} \cdot v^2}{2} \right)}{Power_{dissLoss}(v, P_o)} \cdot v$$

Single Charge Highway Cruise Range Estimate

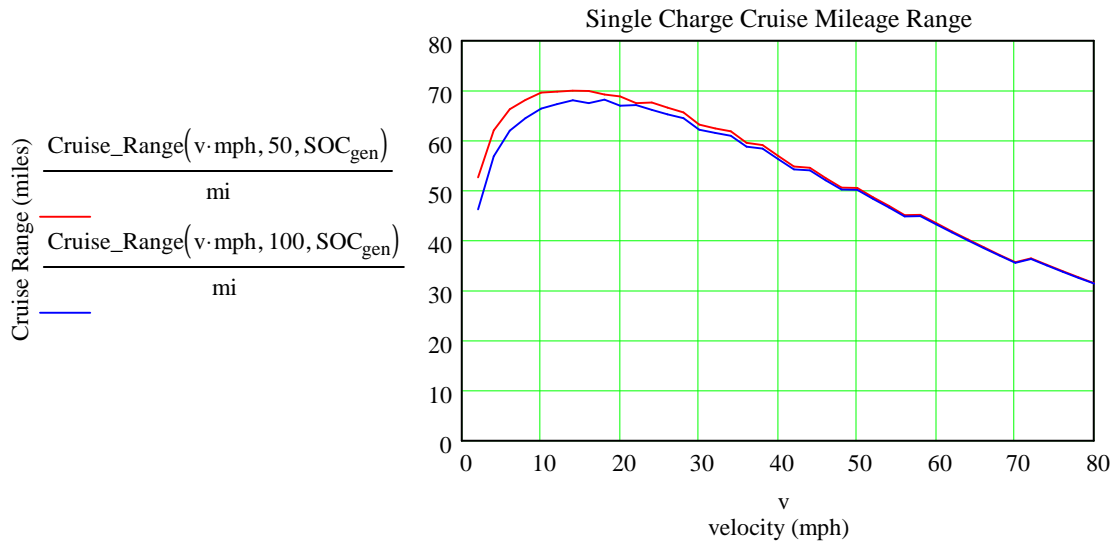
$$\text{Cruise_Range}(30\text{-mph}, 50, \text{SOC}_{\text{gen}}) = 63.21 \text{ mi}$$

$$\text{Cruise_Range}(40\text{-mph}, 50, \text{SOC}_{\text{gen}}) = 56.913 \text{ mi}$$

$$\text{Cruise_Range}(50\text{-mph}, 50, \text{SOC}_{\text{gen}}) = 50.521 \text{ mi}$$

$$\text{Cruise_Range}(60\text{-mph}, 50, \text{SOC}_{\text{gen}}) = 43.465 \text{ mi}$$

$$\text{Cruise_Range}(70\text{-mph}, 50, \text{SOC}_{\text{gen}}) = 35.705 \text{ mi}$$

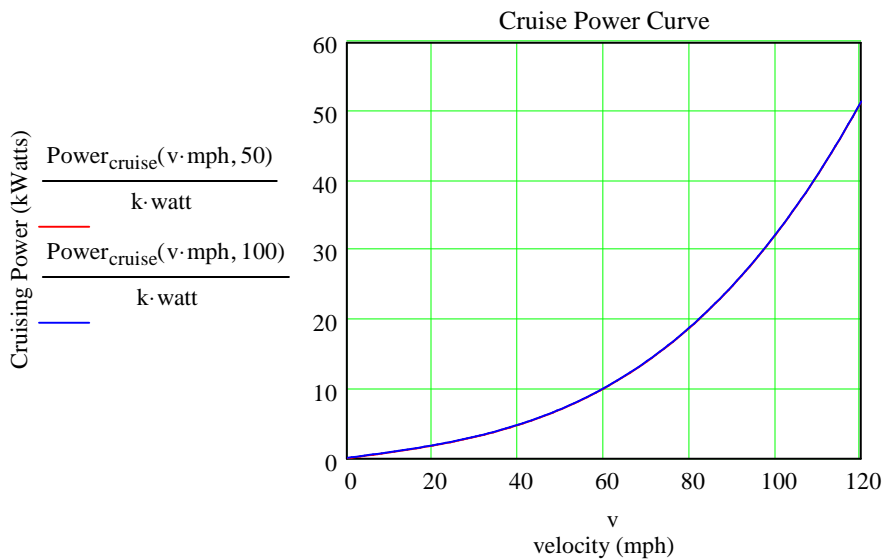


**Single Charge "Highway" Cruise Range @70 mph is 150 mph.
Specsmanship: Twice as much range at 30 mph than 70 mph.
Conclusion: I need a bigger or a better battery!**

Opposing Force Power Dissipation

$$\text{Power}_{\text{cruise}}(v, P_o) := \text{Power}_{\text{dissLoss}}(v, P_o) \quad v := 0, 1..120$$

$$\text{Power}_{\text{cruise}}(60\text{-mph}, 500) = 1.063 \times 10^4 \text{ watt}$$



AER Given Three Different Driving Schedules

Read US06 and FTP Driving Profile Files

<http://www.epa.gov/nvfel/testing/dynamometer.htm>

The US06 cycle represents an 8.01 mile (12.8 km) route with an average speed of 48.4 miles/h (77.9 km/h), maximum speed 80.3 miles/h (129.2 km/h), and a duration of 596 seconds.

The Federal Test Procedure(FTP) is composed of the UDDS followed by the first 505 seconds of the UDDS. It is often called the EPA75. FP10 is a 10 Hz Sampling. HWY10 is the 10 Hz Highway schedule.

FTPF := READPRN("http://www.leapcad.com/Transportation/FedTestProc.TXT")

UDDSF := READPRN("http://www.leapcad.com/Transportation/uddscol.txt")

HWYF := READPRN("http://www.leapcad.com/Transportation/hwycol.txt")

FP10 := READPRN("http://www.leapcad.com/Transportation/FTP10Hz.TXT")

HWY10 := READPRN("http://www.leapcad.com/Transportation/HWY10Hz.txt")

US06F := READPRN("http://www.leapcad.com/Transportation/US06PROFILE.TXT")

Calculate All Electric Range, AER, for Driving Profile Velocity/Time File, P and Sampling Rate, Hz

Regen Efficiency Curve vs Decel (g): $REff(g) := \frac{85}{77} \cdot 0.01 \cdot \left[\left(1 - e^{-27.129 \cdot g} \right) \cdot 91.235 - 28.408 \right]$ $Gg := \frac{\text{mph}}{\text{sec} \cdot g}$

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AER(P, Hz) :=
  Ebat ← E_diss ← v_old ← 0
  n ← -1
  N ← rows(P) - 1
  while E_diss < 8 ∧ n = n
    n ← n + 1
    t ← mod(n, N)
    v ← P_t
    v_avg ← (v + v_old) · 0.5
    P_accel ←  $\frac{k_m \cdot M_{gross} \cdot (v - v_{old}) \cdot \frac{\text{mph} \cdot \text{Hz}}{\text{sec}} \cdot v_{avg} \text{ mph}}{T_{InvE} \cdot GPE}$  if v > v_old
    P_accel ←  $k_m \cdot M_{gross} \cdot (v - v_{old}) \cdot \frac{\text{mph} \cdot \text{Hz}}{\text{sec}} \cdot v_{avg} \text{ mph} \cdot REff \left[ (v_{old} - v) \cdot \text{Hz} \cdot Gg \right]$  otherwise
    E_diss ← E_diss +  $\frac{(\text{Power}_{dissLoss}(v \cdot \text{mph}, 100) + P_{accel}) \cdot \text{sec}}{\text{kW} \cdot \text{hr} \cdot \text{Hz}}$ 
    v_old ← v
    Ebat_n ← E_diss
  R ←  $\sum_{m=0}^n \frac{(P_{\text{mod}(m, N)} + P_{\text{mod}(m+1, N)}) \cdot \text{mph} \cdot \text{sec}}{2 \cdot \text{mi} \cdot \text{Hz}}$ 
  R
  
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t := FTPF^{<0>} FTP := FTPF^{<1>} UDDS := UDDSF^{<1>}

HWY := HWYF^{<1>} R_{hwy} := rows(HWY)

r1 := 0..rows(HWY10)·10 - 1 time := US06F^{<0>} US06 := US06F^{<1>} n₆ := 0..598

$HWY10V := \text{submatrix}(HY10, 0, \text{rows}(HY10) - 1, 1, \text{cols}(HY10) - 1)$
 $HWY10_{r1} := HWY10V_{\text{ceil}\left(\frac{r1+1}{10}\right)-1, \text{mod}(r1, 10)}$
 $FTP10V := \text{submatrix}(FP10, 0, \text{rows}(FP10) - 1, 1, \text{cols}(FP10) - 1)$

$AER(US06, 1) = \blacksquare$ **$AER(FTP, 1) = 40.183$** $AER(HWY, 1) = 41.96$ $AER(HWY10, 10) = \blacksquare$

EPA 20085 Cycle MPG Fuel Economy Least Squares Fit Regression for AER

$$MPG_{city} := \frac{1}{\left(0.003259 + \frac{1.18053}{AER(FTP, 1)}\right)} \quad MPG_{city} = 30.639 \quad MPG_{hwy} := \frac{1}{0.001376 + \frac{1.3466}{AER(HWY, 1)}} \quad X := \frac{1}{40}$$

$MPG_{epa} := 0.55 \cdot MPG_{city} + 0.45 \cdot MPG_{hwy}$ **$MPG_{epa} = 30.297$**

$$r := 0.. \text{rows}(FTP) - 1 \quad \text{Distance}_r := \sum_{r=0}^r FTP_r \cdot \frac{10}{60 \cdot 60} \quad rr := 0.. \text{rows}(US06) - 1 \quad \text{Distance}_{rr} := \sum_{rr=0}^{rr} US06_{rr} \cdot \frac{10}{60 \cdot 60}$$

$\text{max}(\text{Distance}) = 110.414$ $\text{max}(\text{Distance}_{rr}) = 80.08$

$WRITEPRN("EFTP.PRN") := AER(FTP, 1) \cdot 40$ $E_{FTP} := READPRN("EFTP.PRN")$ $\text{max}(E_{FTP}) \cdot X = 37.125$
 $WRITEPRN("EUS06.PRN") := AER(US06, 1) \cdot 40$ $E_{US06} := READPRN("EUS06.PRN")$ $\text{max}(E_{US06}) \cdot X = 27.424$
 $WRITEPRN("EHWY.PRN") := AER(HWY, 1) \cdot 40$ $E_{HWY} := READPRN("EHWY.PRN")$ $\text{max}(E_{HWY}) \cdot X = 39.05$

